



HOCHSCHULE RUHR WEST  
UNIVERSITY OF APPLIED SCIENCES

# Time-variant Current Modeling Corresponding to Access Impedance Measurements on the Power Line Network

*WSPLC 17, Prague, Czech Republic  
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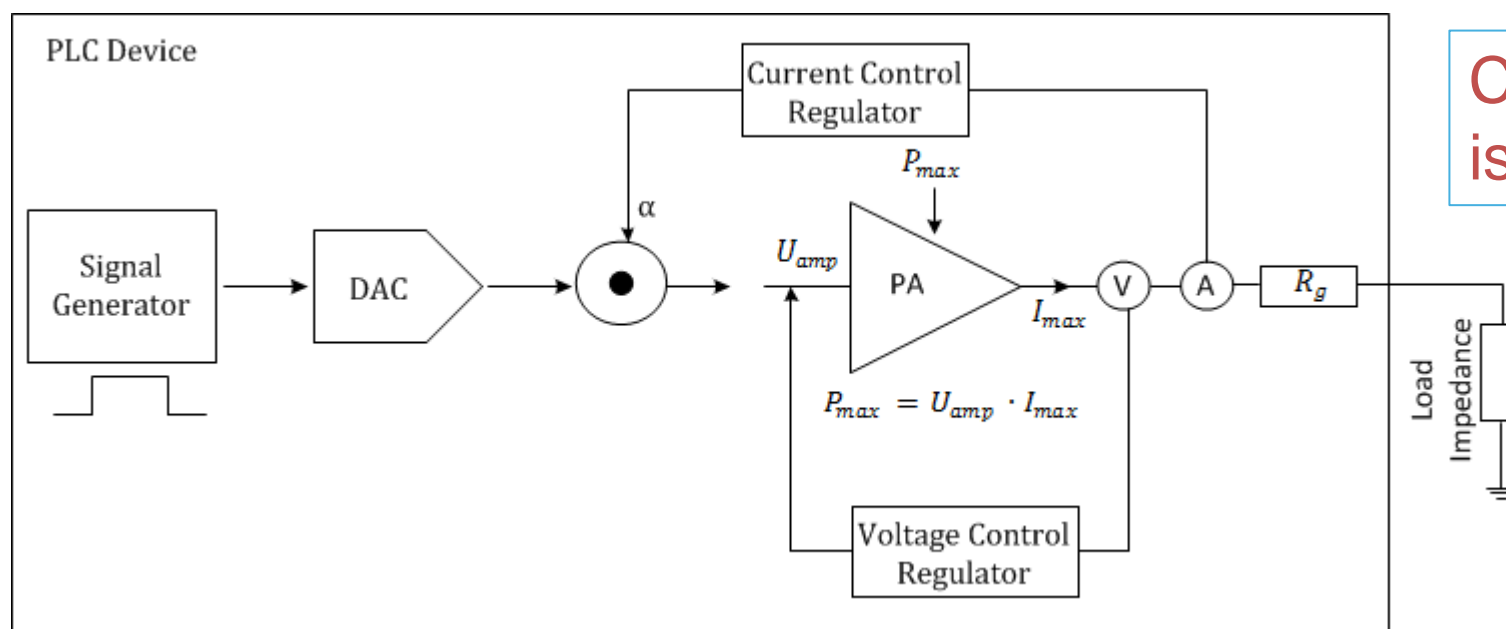
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# Outline

- Problem statement
- Current modeling algorithm
- Simulation results
- Conclusion

## Problem statement

- The Power Line Communication (PLC) channel characteristics affected by the connected loads.
- Access impedance of the PLC channel is time and frequency variant.
- Reduction of the power amplifier output level of PLC devices.

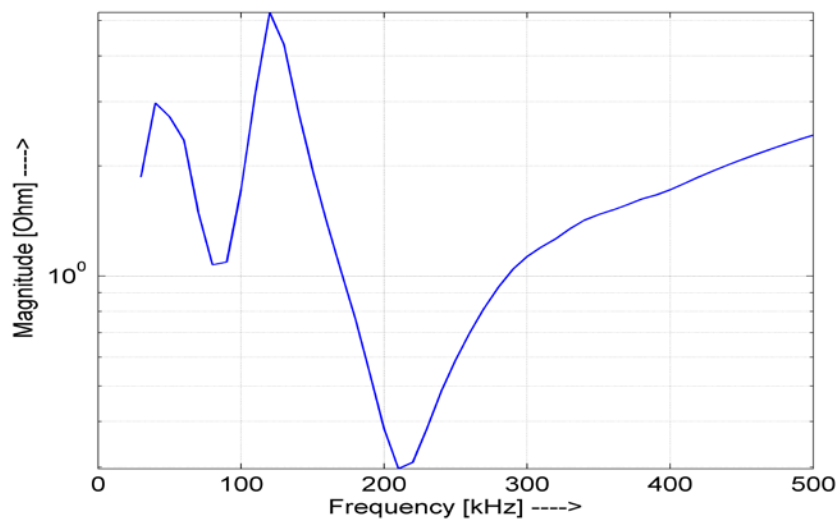
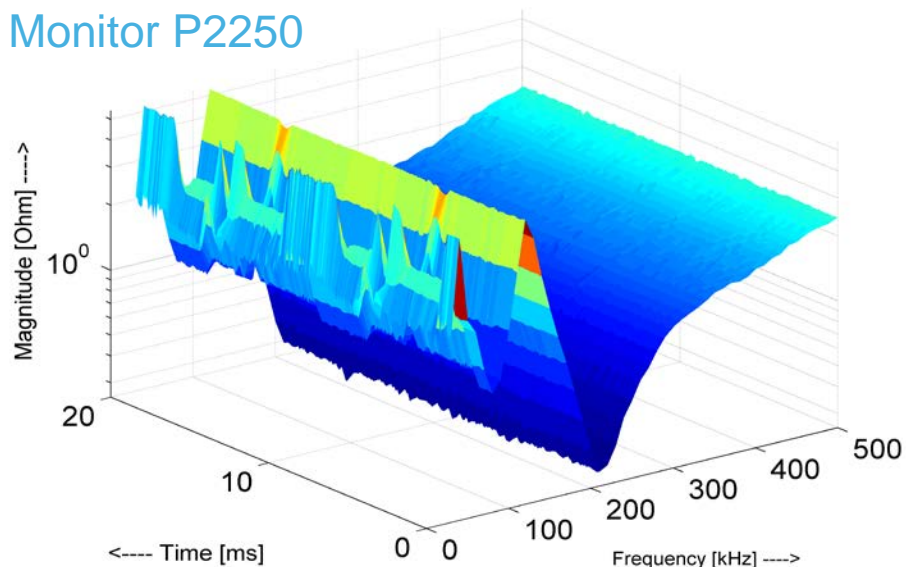


Current Modeling  
is needed!

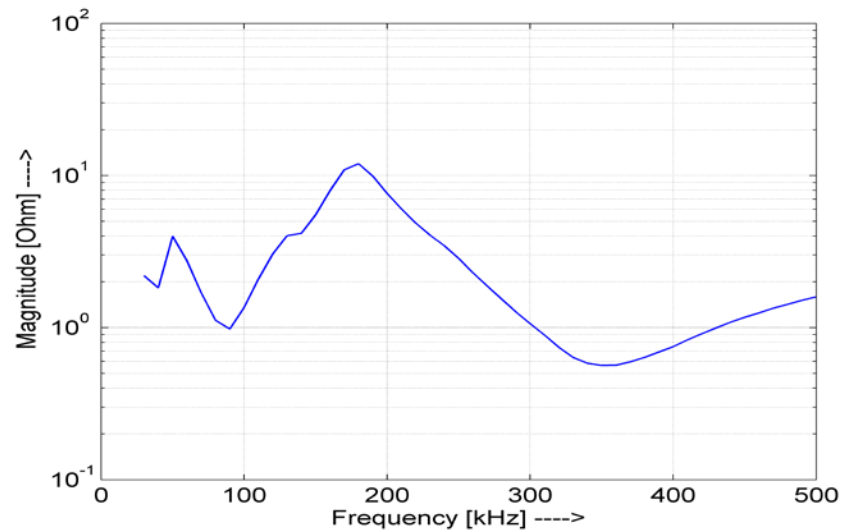
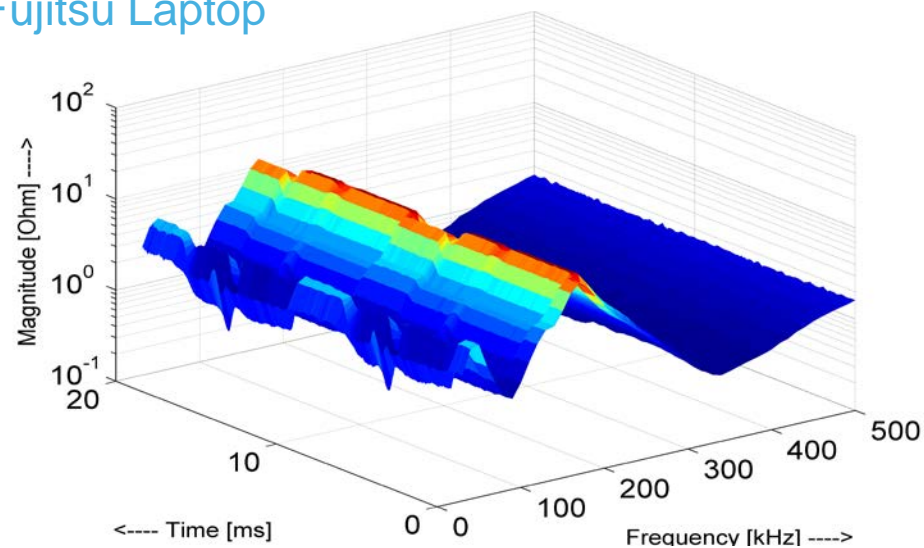
# Access impedance problem

- Impedance is very low and time variant!

## Monitor P2250

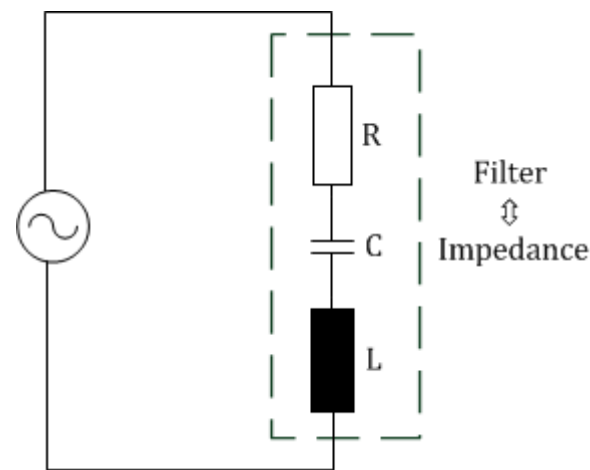
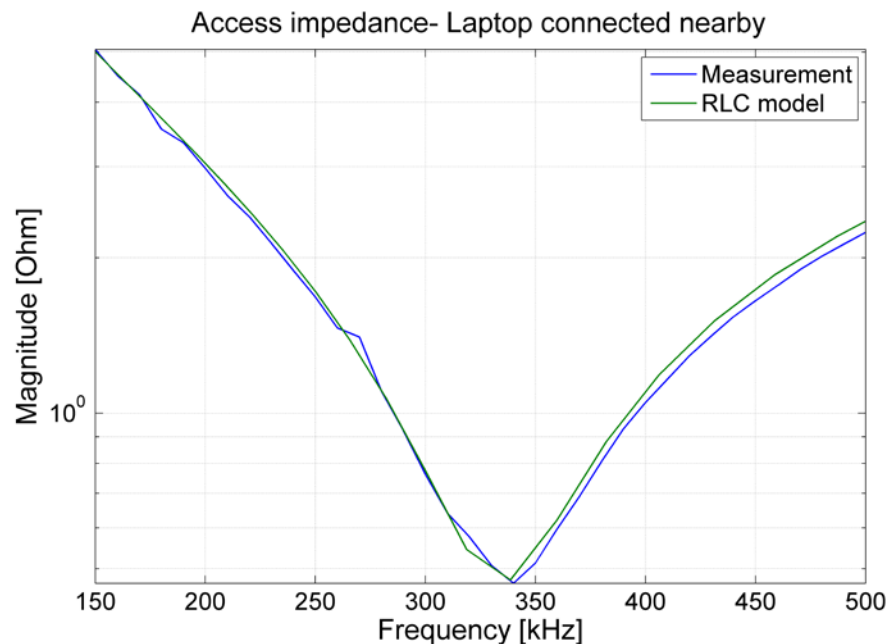


## Fujitsu Laptop



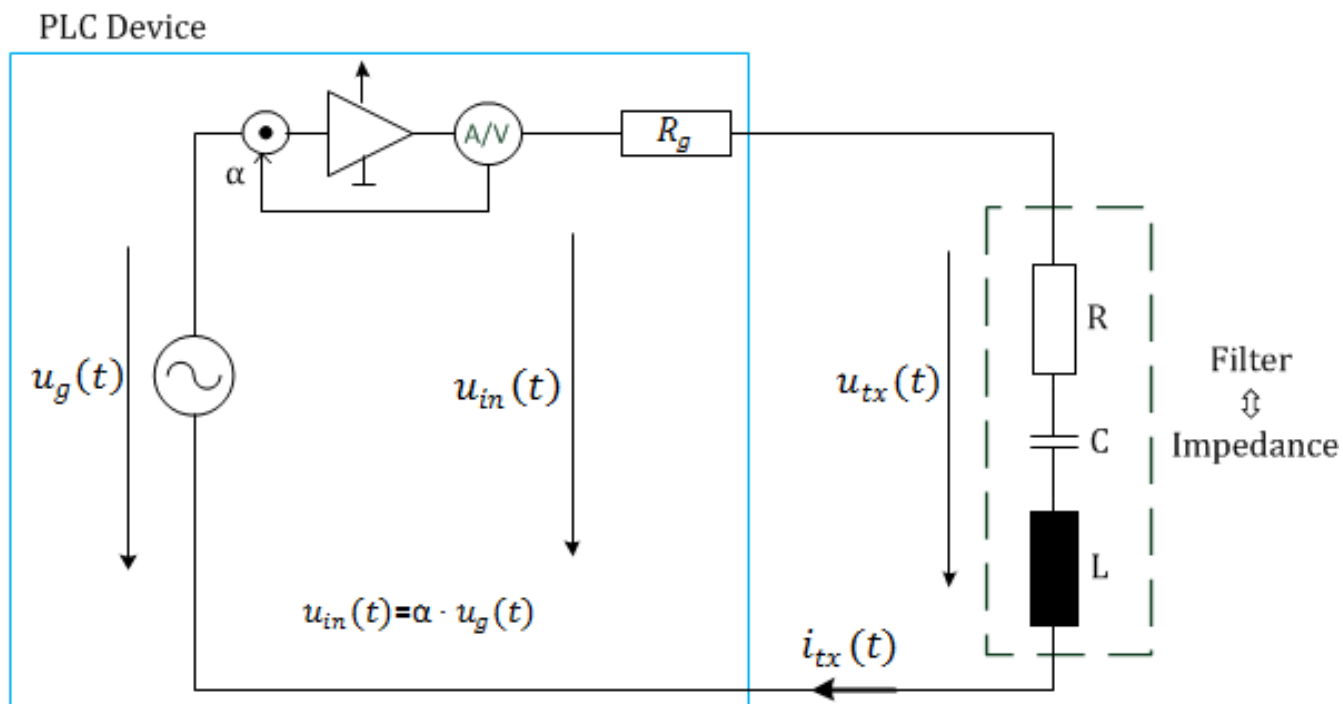
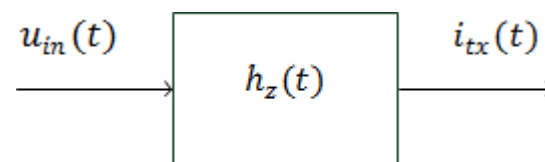
## Current modeling algorithm (1/4)

- Filter design based RLC circuit that represents the impedance behavior.
- RLC Filter parameters are based Spice simulation.
- $R= 0.47 \text{ Ohm}$ ,  $C= 0.17 \text{ } \mu\text{F}$ ,  $L=1.33 \text{ } \mu\text{H}$ .



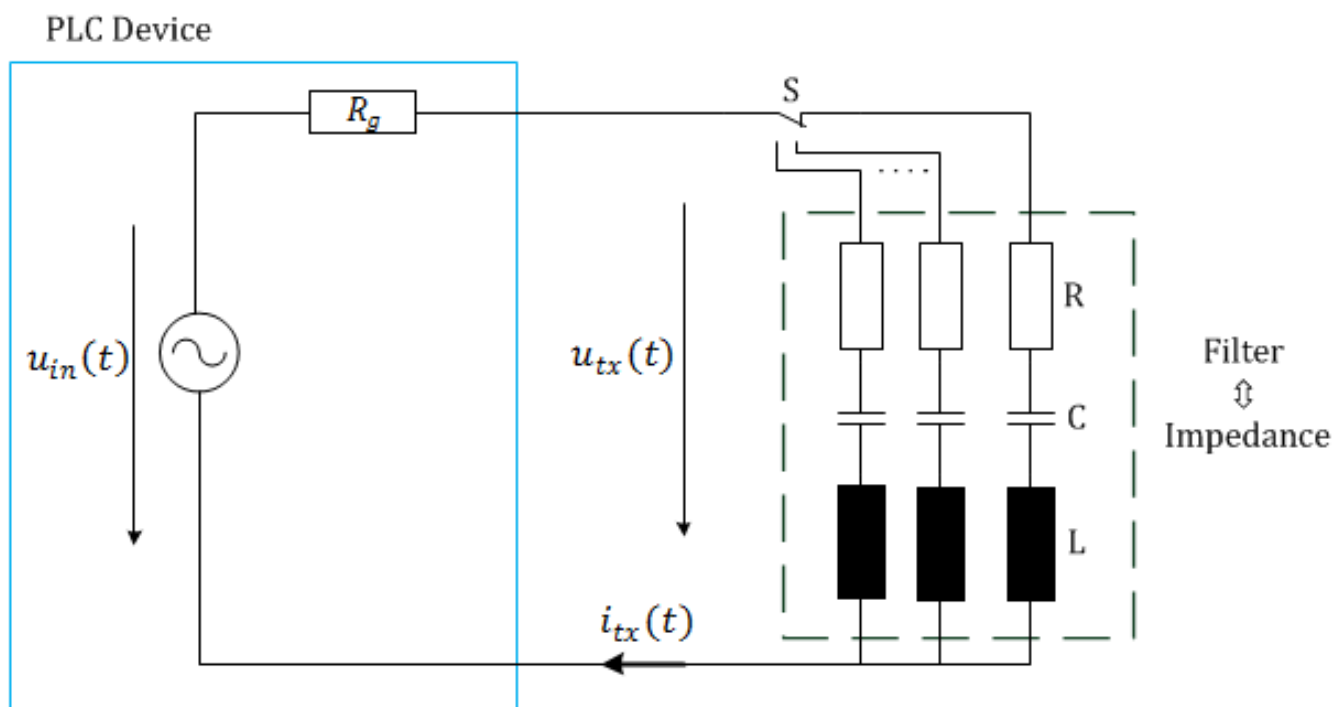
## Current modeling algorithm (2/4)

- Linear system view is considered.
- $i_{tx}(t) = u_{in}(t) * h_z(t)$ ;  
 $h_z(t)$  is the impulse response of the RLC filter



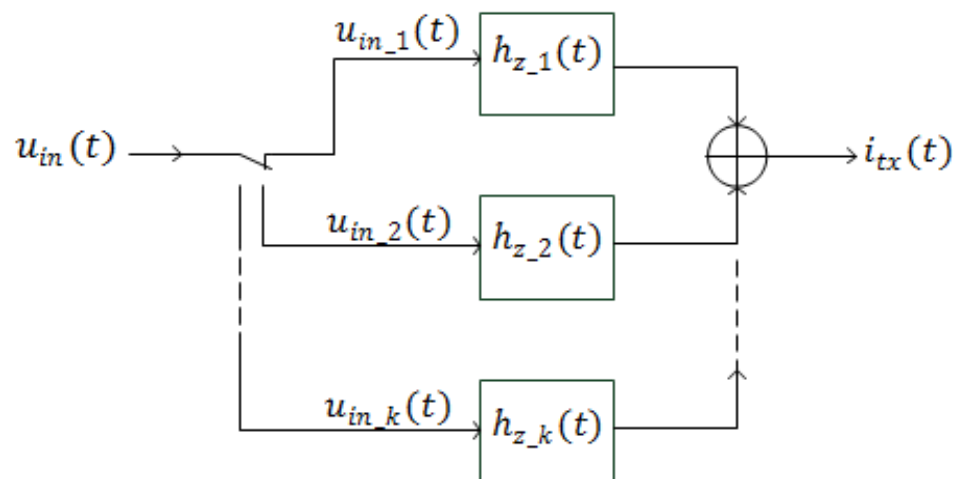
## Current modeling algorithm (3/4)

- Toggle switch for current analysis.
- Monitoring the current behavior at the specific time slots where the impedance is relatively constant.



## Current modeling algorithm (4/4)

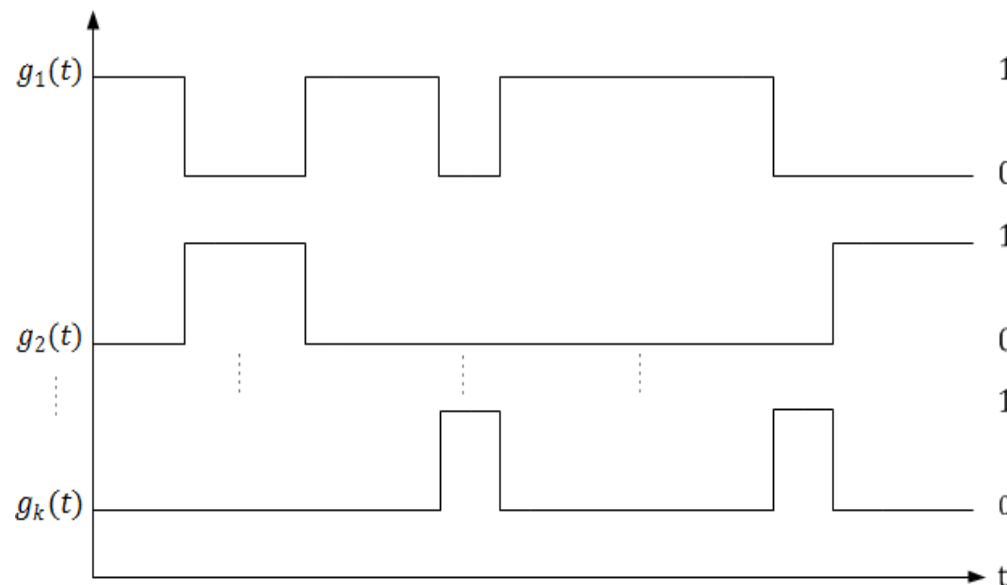
- $i_{tx}(t) = \sum_{k=1}^K u_{in\_k}(t) * h_{z\_k}(t)$ ;  $K$  is number of filters.



- $u_{in\_k}(t) = u_{in}(t) \cdot g_k(t)$ ;

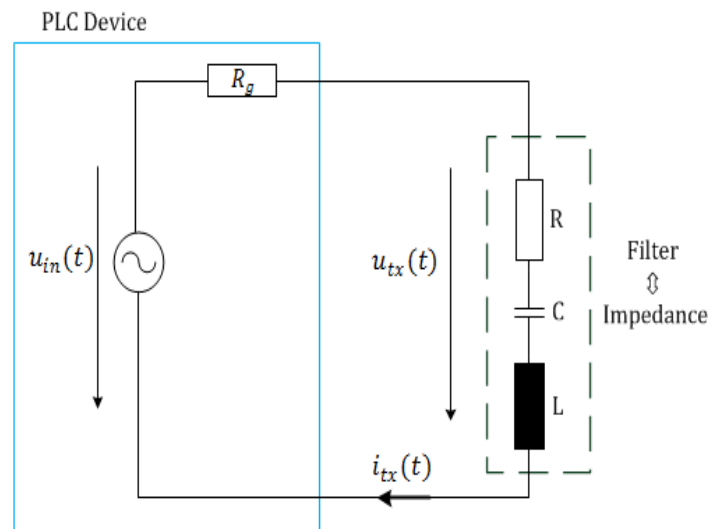
$$g_k(t) = \begin{cases} g_k(t) \in \{0; 1\} \\ \sum_{k=1}^K g_k(t) = 1 \\ g_k(t) = g_k(t + l \cdot T_p) \end{cases} ;$$

$l \in \mathbb{Z}$  and  $T_p$  is the time period over the mains frequency.

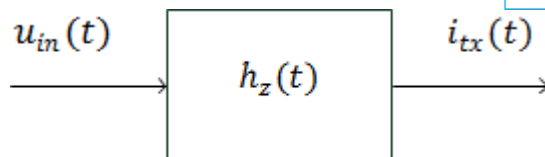


## Filter design (1/2)

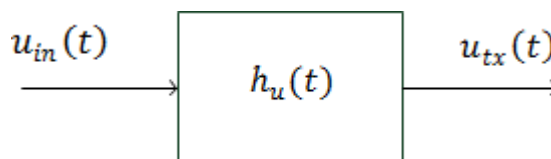
- Filter design based Laplace transformation.



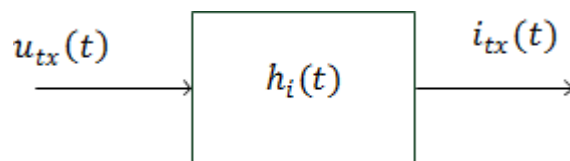
- $$H_z(s) = \frac{sC}{s^2CL + sC(R + R_g) + 1}$$



- $$H_u(s) = \frac{s^2CL + sCR + 1}{s^2CL + sC(R + R_g) + 1}$$

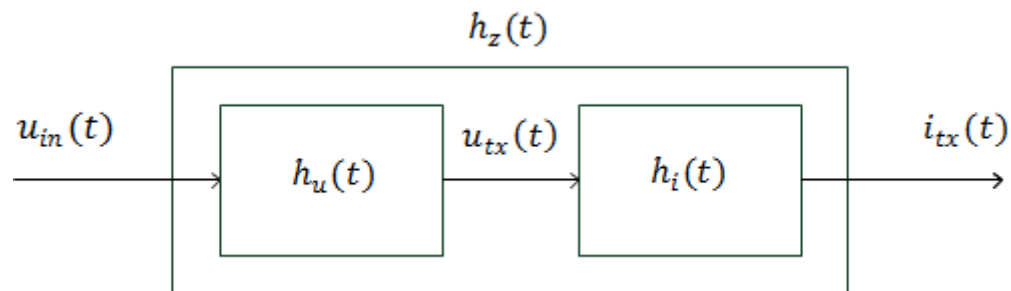


- $$H_i(s) = \frac{sC}{s^2CL + sCR + 1}$$



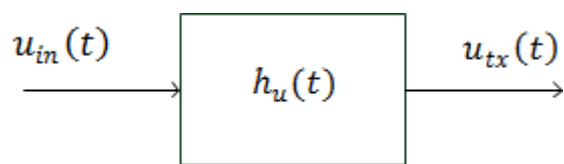
- Full system model:  

$$H_z(s) = H_u(s) \cdot H_i(s)$$

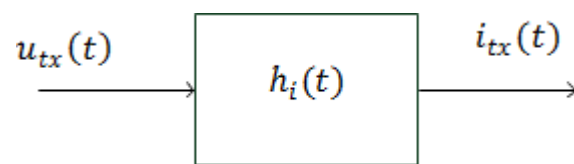
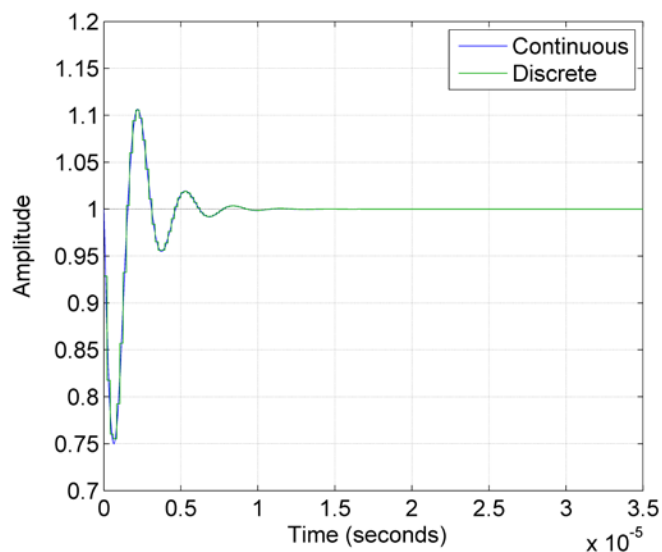


## Filter design (2/2)

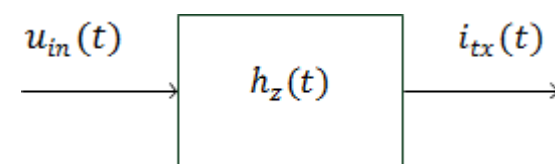
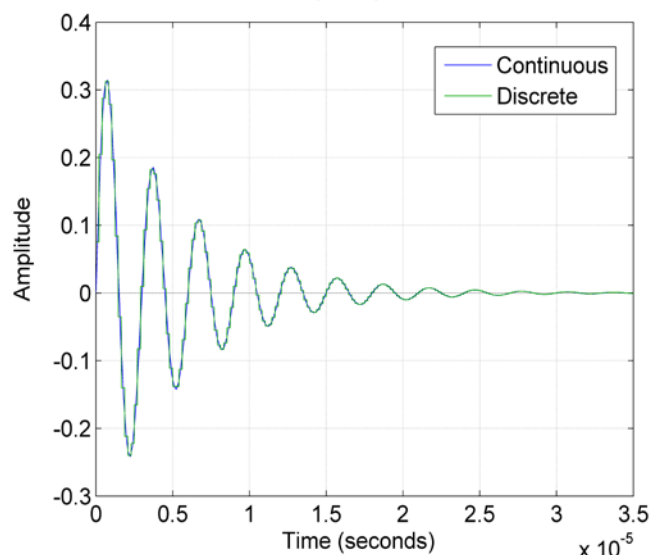
- S-domain to Z-domain using First-order hold (FOH) method.



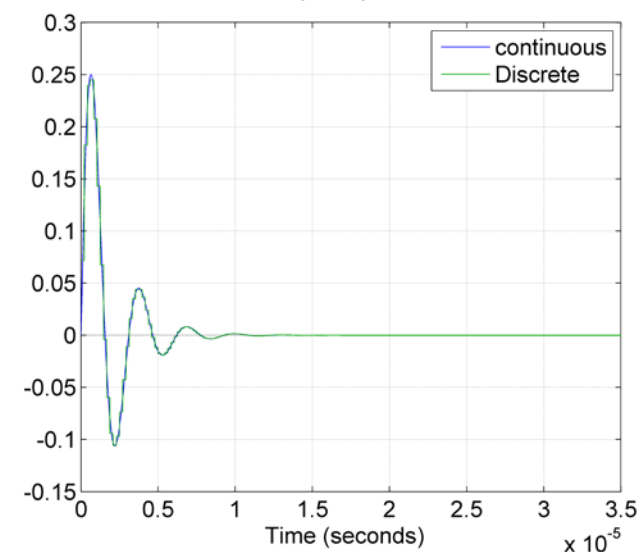
Step Response



Step Response



Step Response

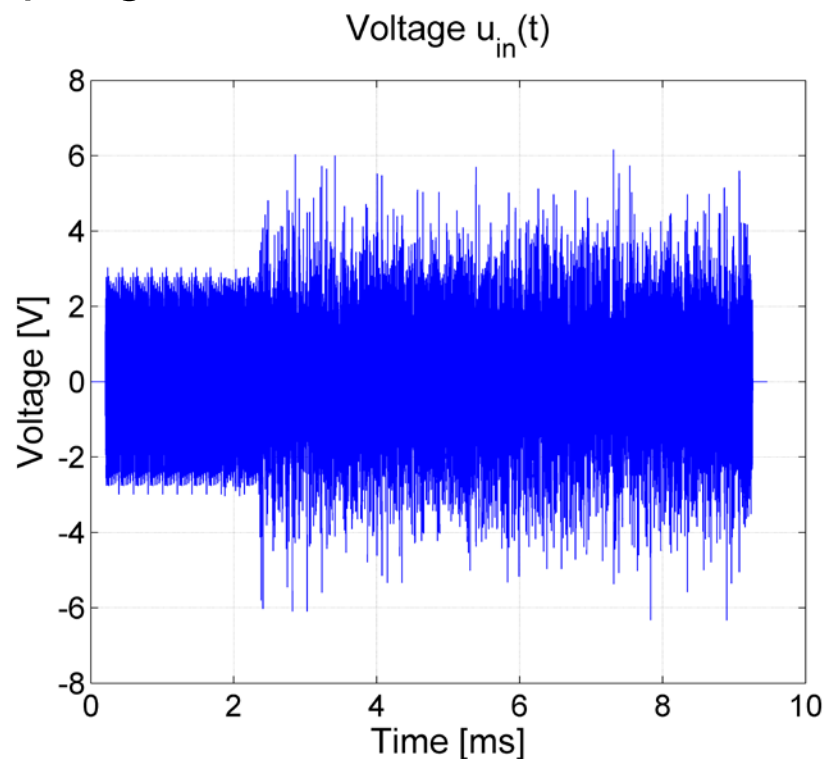


## Simulation Results (1/3)

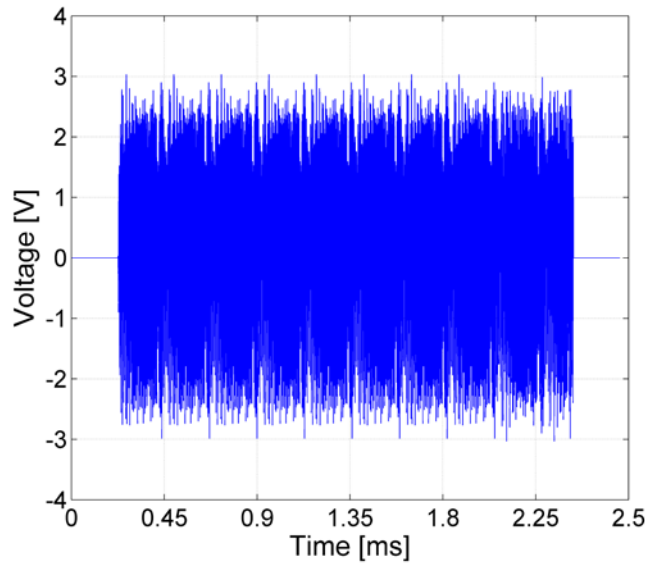
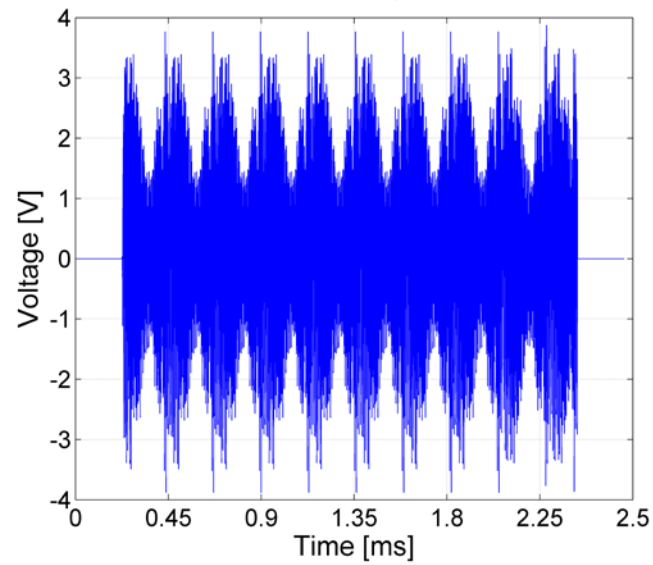
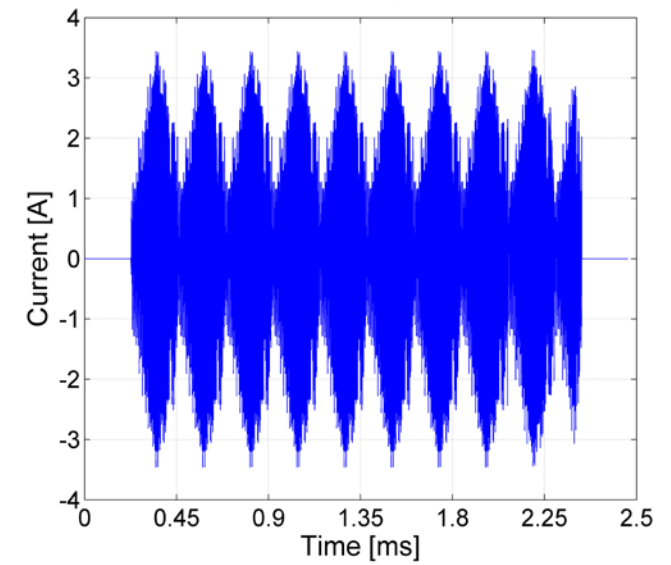
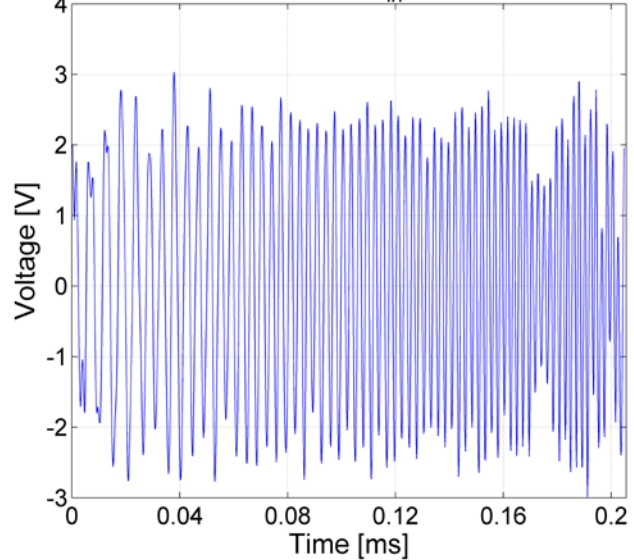
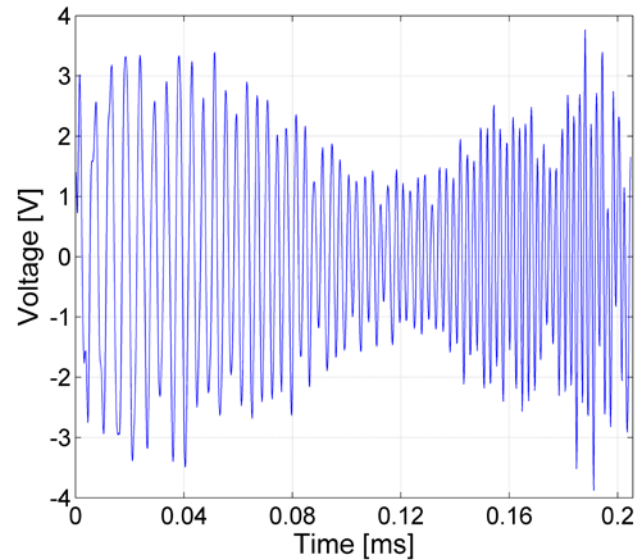
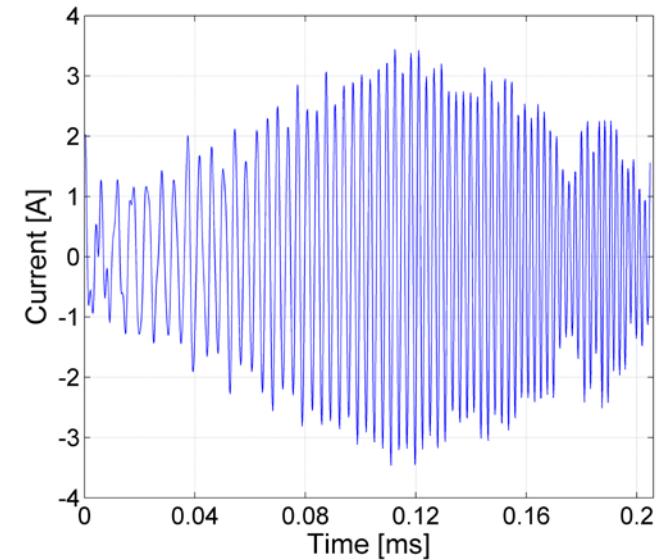
- Transmitted signal based NB PLC IEEE 1901.2: (9.5 preamble+12 FCH+ data)
- We consider the signal preamble for evaluation.
- IEEE 1901.2 signal preamble are chirp signals.

### Simulation parameters

FCC-above-CENELEC	154.6875 to 487.5 kHz
Sampling frequency	1.2 MHz

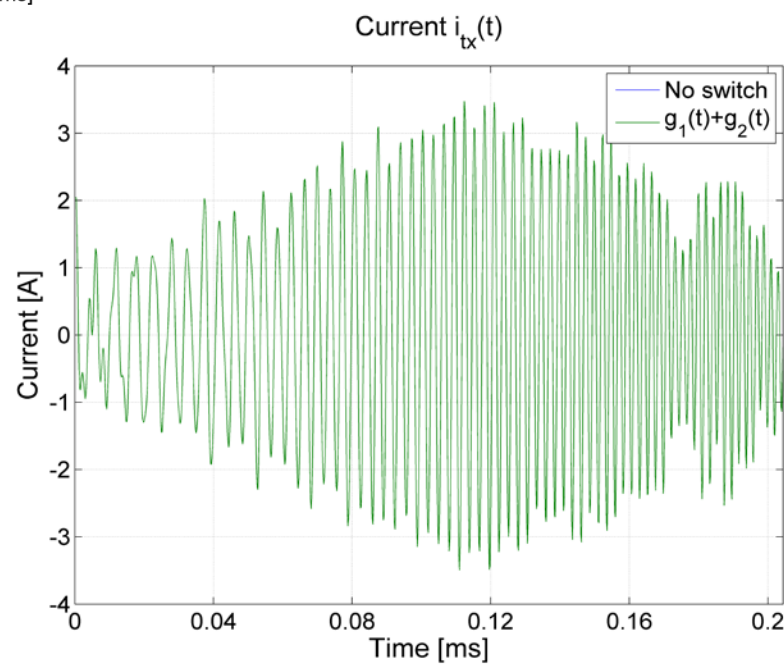
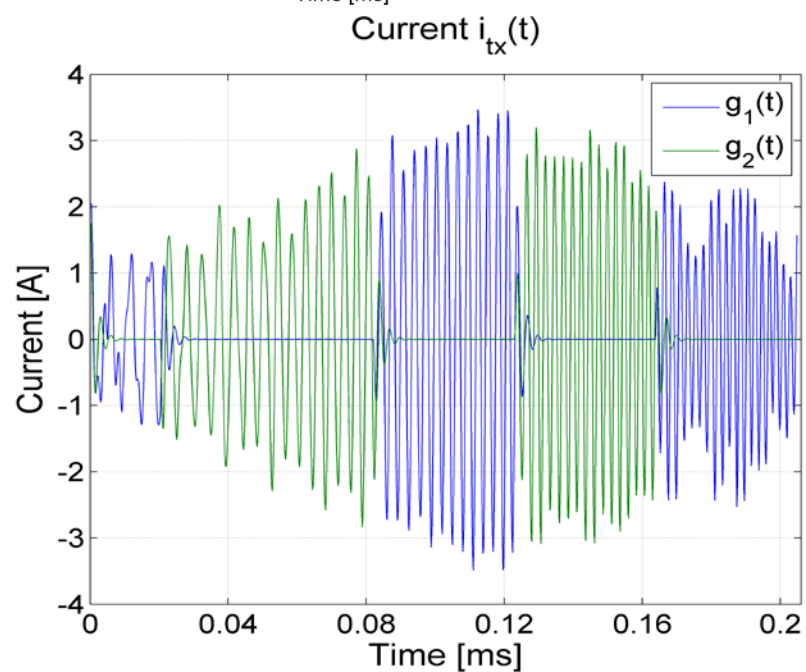
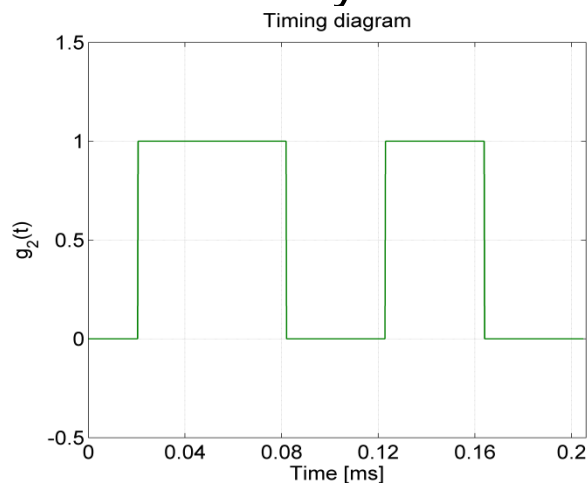
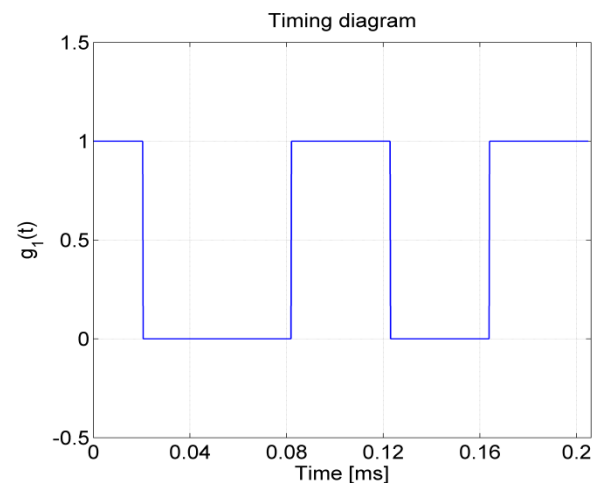


# Simulation Results (2/3)

Voltage  $u_{in}(t)$ Voltage  $u_{tx}(t)$ Current  $i_{tx}(t)$ Voltage  $u_{in}(t)$ Voltage  $u_{tx}(t)$ Current  $i_{tx}(t)$ 

# Simulation Results (3/3)

- Method verification of current analysis in respect to time variation .



## Conclusion

- Time variant electrical current modeling of PLC devices corresponding to access impedance measurement is presented.
  - The modeling algorithm based RLC filter design.
  - This model allowed the analysis of the current behavior in respect to time to optimize the transmitted signal of PLC devices.
- **Future works:**
- Find the current model using frequency method.
  - Simulation results comparison and verification.

**Thank you for  
your attention!**

